

1. Consider the following population density model:

$$N_{t+1} = 2 - (N_t - 1)^2$$

(a) (7 pts.) Find the non-negative fixed point(s) and analyze their stability.

$$N^* = 2 - (N^* - 1)^2$$

$$N^* = 2 - (N^{*2} - 2N^* + 1)$$

$$N^{*2} - N^* - 1 = 0$$

$$N_{1,2}^* = \frac{1 \pm \sqrt{1^2 - 4(-1)}}{2} = \frac{1 \pm \sqrt{5}}{2}$$

$$N_1^* = \frac{1 - \sqrt{5}}{2} < 0 \quad \text{negative}$$

$$N_2^* = \frac{1 + \sqrt{5}}{2} > 0 \quad \checkmark$$

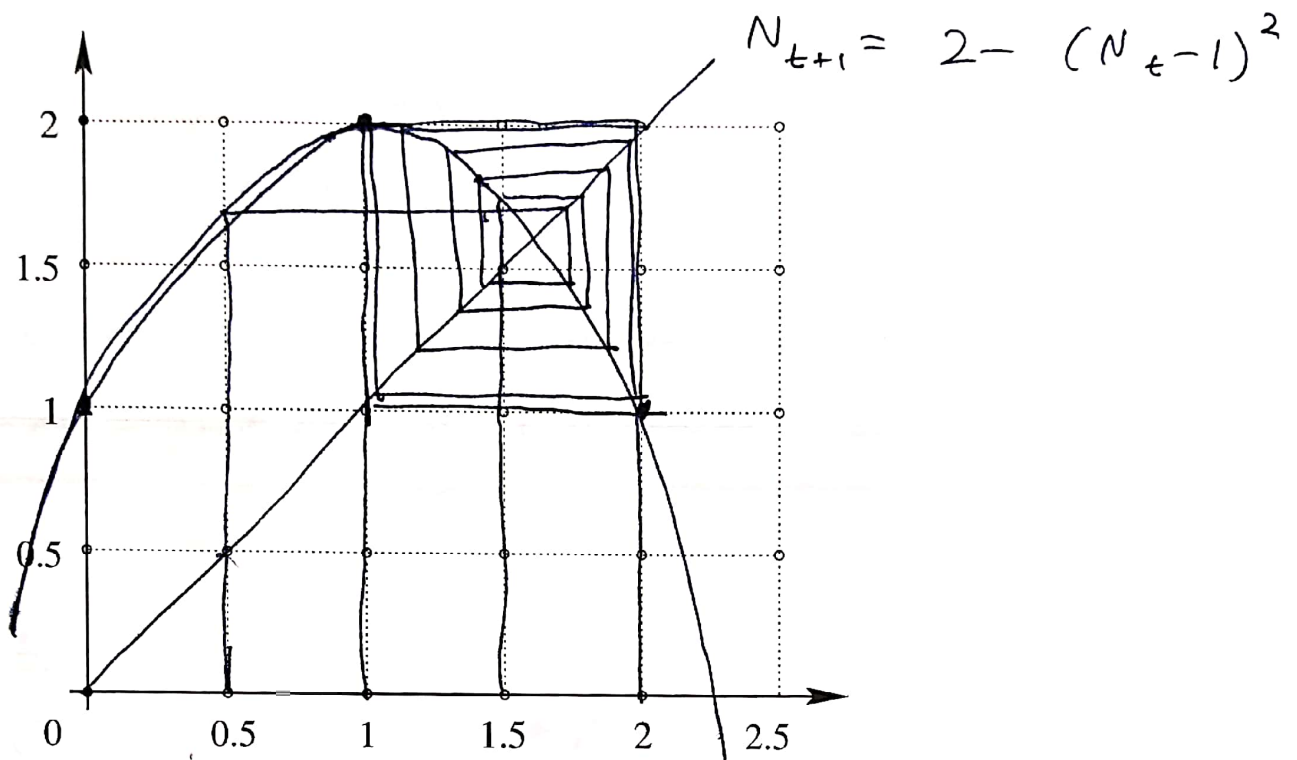
$$f(N) = 2 - (N - 1)^2 \Rightarrow f'(N) = -2(N - 1)$$

$$\left| -2 \left( \frac{1 + \sqrt{5}}{2} - 1 \right) \right| \stackrel{?}{<} 1$$
$$= \frac{-1 + \sqrt{5}}{2}$$
$$\sqrt{5} - 1$$

$$|\sqrt{5} - 1| = \sqrt{5} - 1 > 1$$

Then  $N_x^* = \frac{1 + \sqrt{5}}{2}$  is unstable.

- (b) (10 pts.) Carefully draw the cobwebs for the following five initial conditions:  $N_0 = 0.5, 1, 1.5, 2$ . Do enough iterations to estimate the long term behavior for each solution. Describe and compare the long term behaviors of these four solutions.



$f(N) = 2 - (N-1)^2$  This is the same figure as  $-N^2$ ; but shifted one unit right, and two units up.  
 $f(0) = 1, f(1) = 2, f(2) = 1$

For  $N_0 = 1, N_1 = N_3 = N_5 = \dots = 2$  and  $N_2 = N_4 = N_6 = \dots = 1$

For  $N_0 = 2, N_1 = N_3 = N_5 = \dots = 1$  and  $N_2 = N_4 = N_6 = \dots = 2$

For  $N_0 = 0.5$  and  $N_0 = 1.5$ ;  $N_t$  appears to converge to the same two-cycle;  $1 \leftrightarrow 2$ ; whereas  $N_0 = 1$  &  $N_0 = 2$  already start on the same 2-cycle.

2. (10 pts.) Find all fixed points of the following discrete predator-prey model:

$$x_{n+1} = 4x_n(1 - x_n) - 4x_n y_n$$

$$y_{n+1} = 4x_n y_n - y_n$$

$$\begin{aligned} x^* &= 4x^*(1 - x^*) - 4x^*y^* = 4x^*(1 - x^* - y^*) \\ y^* &= 4x^*y^* - y^* = y^*(4x^* - 1) \\ 0 &= 4x^*\left(\frac{3}{4} - x^* - y^*\right) \\ 0 &= \underbrace{2y^*}_{y^*=0} \underbrace{(2x^* - 1)}_{x^*=1/2} \end{aligned}$$

Case 1

$$\begin{aligned} y^* = 0 \Rightarrow 0 &= 4x^*\left(\frac{3}{4} - x^*\right) \\ &\quad \underbrace{x^*=0} \quad \underbrace{x^*=3/4} \\ &\quad \underline{(0, 0)} \quad \underline{(3/4, 0)} \end{aligned}$$

Case 2

$$\begin{aligned} x^* = 1/2 \Rightarrow 4 \frac{1}{2} \left(\frac{3}{4} - \frac{1}{2} - y^*\right) &= 0 \\ &\quad \underbrace{y^* = \frac{1}{4}} \\ &\quad \underline{(1/2, 1/4)} \end{aligned}$$

Three fixed points:

- $(0, 0)$
- $(3/4, 0)$
- $(1/2, 1/4)$

3. Consider the following differential equation model.

$$u' = u - uv$$

$$v' = 2u - 6v$$

(a) (10 pts.) Find all fixed points, analyze their stability, and classify them (e.g. stable node, center, saddle, etc.) Is coexistence possible?

Fixed points =

$$y \quad u' = u(1-v) = 0 \Rightarrow \text{Either } u=0 \text{ or } v=1$$

Case 1. Let  $u=0$ , then  $v' = -6v = 0 \Rightarrow v=0$   
(0, 0)

Case 2. Let  $v=1$ , then  $v' = 2u - 6 = 0 \Rightarrow u=3$   
(3, 1)

$u$ - Nullcline(s) :  $u' = u(1-v) = 0 \Rightarrow$   $u=0$

$v$ - Nullcline(s) =  $2u - 6v = 0 \Rightarrow$   $v=1$   
 $v = \frac{1}{3}u$

$$J(u,v) = \begin{bmatrix} 1-v & -u \\ 2 & -6 \end{bmatrix}$$

$$J(0,0) = \begin{bmatrix} 1 & 0 \\ 2 & -6 \end{bmatrix} \det = -6 < 0 \Rightarrow \underline{\text{saddle}}$$

$$J(3,1) = \begin{bmatrix} 0 & -3 \\ 2 & -6 \end{bmatrix} \det = 0 - (-6) = 6 > 0 \Rightarrow \text{not saddle}$$

$$\text{tr} = -6 < 0 \Rightarrow \underline{\text{stable}}$$

$$(\text{Trace})^2 - 4(\text{Det}) = 36 - 4 \cdot 6 = 36 - 24 = 12 > 0 \Rightarrow \text{not saddle.}$$

stable node

Coexistence is possible; as there is a positive stable fixed point, (3,1).

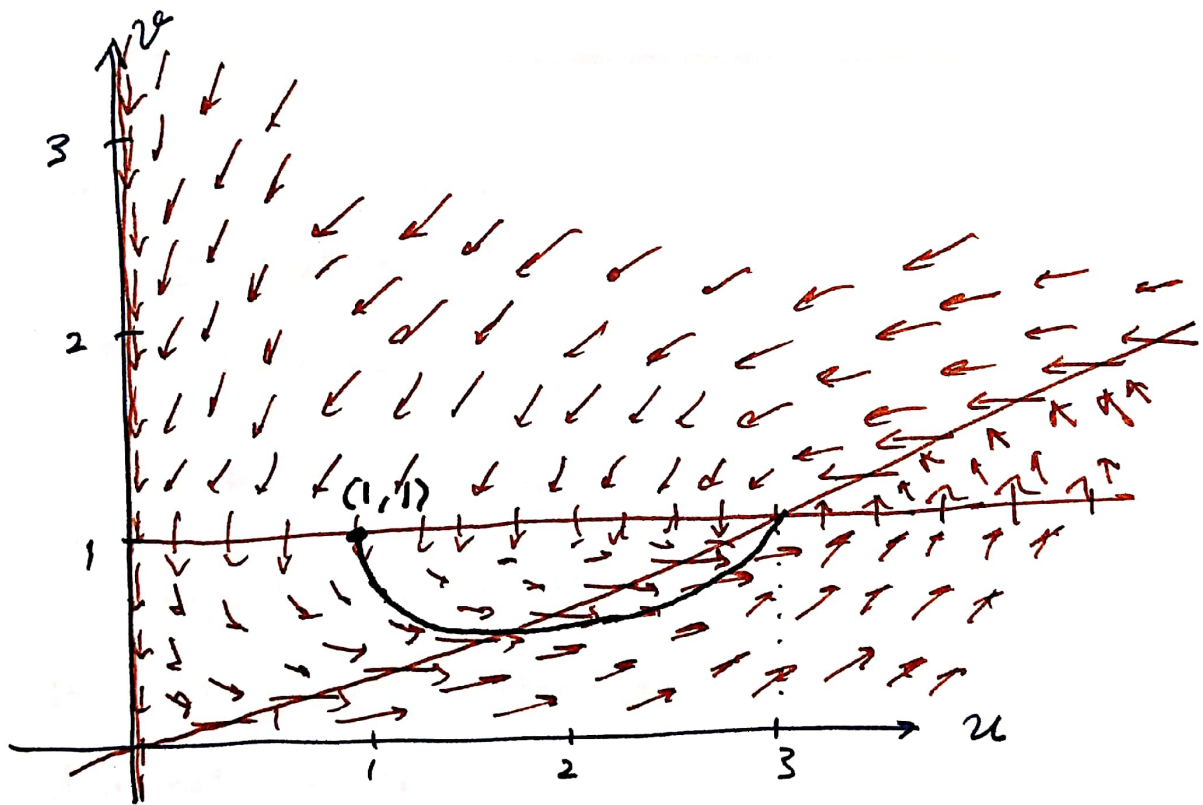
(b) (10 pts.) Do the phase plane analysis. In other words, find and sketch the null-clines, and the phase portrait (direction field). Focus only on the first quadrant ( $u \geq 0, v \geq 0$ ). Draw a rough sketch of the solution with initial conditions  $u(0) = 1, v(0) = 1$ .

$$u\text{-Nullclines: } u' = u - uv = \underbrace{u(1-v)} = 0$$

$$\underline{\underline{u=0}} \quad \underline{\underline{v=1}}$$

$$v\text{-Nullclines: } v' = 2u - 6v = 2(u - 3v) = 0$$

$$\underline{\underline{v = \frac{1}{3}u}}$$



For high  $u$  & low  $v$ :  $u' > 0$   $v' > 0$

For low  $u$  & high  $v$ :  $u' < 0$   $v' < 0$

4. Fill in the blanks or identify the statement as True or False.

- (a) (2 pts.) In problem 2,  $x$  represents the predator, and  $y$  represents the prey. ( True  / False  )
- (b) (2 pts.) Carrying capacity of the model  $x_{n+1} = 2x_n(1 - \frac{x_n}{6})$  is 3. Accepted 6 as well.
- (c) (2 pts.) If the model  $x_{n+1} = f(x_n)$  has a 2-cycle, such that  $a = f(b)$  and  $b = f(a)$ , then there exists a fixed point  $c$  between  $a$  and  $b$ . ( True  / False  ) Accept both options
- (d) (2 pts.) A fixed point of the model  $x_{n+1} = f(x_n)$  is also a fixed point of the second iterate map  $y_{n+1} = f(f(y_n))$ . ( True  / False  )
- (e) (2 pts.) For the model  $x_{n+1} = f(x_n)$ , if there exists values  $a$  and  $b$  such that  $a = f(b)$  and  $b = f(a)$ , then both  $a$  and  $b$  are stable fixed points of the second iterate map  $y_{n+1} = f(f(y_n))$ . ( True  / False  )
- (f) (2 pts.) Liapunov exponent of the model in the first problem is negative. ( True  / False  )
- (g) (2 pts.) If the Liapunov exponent of a model is positive, then it has no fixed points. ( True  / False  )

(a) Interaction term ( $4xy$ ) benefits  $y$ ,

$$(b) \quad x^* = 2x^*(1 - \frac{x^*}{6})$$

$$0 = 2x^*(\frac{1}{2} - \frac{x^*}{6}) \Rightarrow \underline{x^* = 3}$$

(c)  $f$  has to be continuous.

(e) It does not have to be stable

(f) It is not chaotic. There exists a stable 2-cycle.

(g) Just not stable.